

CERTIFICATE OF CONSTANCY OF PERFORMANCE

Issued by DBI Certification, notified body No. 2531.

In compliance with *Regulation 305/2011/EU of the European Parliament and of the Council of 9 March 2011* (the Construction Products Regulation or CPR), this certificate applies to the construction product

Optical smoke and heat detector AUTRONICA BHH-320 with integrated short-circuit isolator

The product fulfils the essential characteristic:

	See Annex 1
Intended use:	Applications related to automatic fire alarm systems
Placed on the market under the name	or trade mark of:
	Autronica Fire and Security AS
	Bromstadvegen 59
	NO-7047 Trondheim
	Norway
and produced in the manufacturing pl	ant:
	CPA10058
This attests that all provisions concern	ning the performance described in Annex ZA of the standard(s)
EN 54-5:2017/A1:2018 :	Fire detection and fire alarm systems - Part 5: Heat detectors - point heat detectors

:	Fire detection and fire alarm systems - Part 5: Heat detectors - point heat detectors
:	Fire detection and fire alarm systems - part 7: Smoke detectors - Point smoke
	detectors that operate using scattered light, transmitted light or ionization
:	Fire detection and fire alarm systems - Part 17: Short-circuit isolators
	: : :

under system 1 for the performance set out in this certificate are applied and that the factory production control conducted by the manufacturer is assessed to ensure the

CONSTANCY OF PERFORMANCE OF THE CONSTRUCTION PRODUCT.

This certificate was first issued on 2022-08-09 and will remain valid as long as neither the harmonised standard, the construction product, the AVCP methods nor the manufacturing conditions in the plant are modified significantly, unless suspended or withdrawn by the notified product certification body.

The attached annexes form part of this certificate.

Date of issue: 2022-08-09.

Merete Poulsen Responsible for evaluation

Steen Nilsson Responsible for certification decision

DANAK Prod. Reg. Nr. 7023

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DBI Certification A/S Jernholmen 12, 2650 Hvidovre Tlf.: 36 34 90 90

E-mail: info@dbicertification.dk www.dbicertification.dk

Version 2022-02-08 Page **1** of **10**



Annex 1

EXTENT

Model Reference:

Optical smoke and heat detector AUTRONICA BHH-320 with integrated short-circuit isolator.

Kit BH-XXX = BHH-XXX and BWA-100

Variants:

Optical Smoke and Heat detector				
Brand	Class (Heat)			
Autronica	BHH-220	A1		
Autronica	BHH-520	A1		
Autronica	BHH-520/N	A1		
Autronica	BHH-520/EX	A1		

Base:

BWA-100 (Conventional)

Operating Voltage:

10 to 27 V DC

Heat Response Catergory:

Table 1

- 14					
	Detector Category	Typical Application	Maximum	Minimum Static	Maximum Static
	(Heat Class):	Temperature	Application	Response	Response
			Temperature °C	Temperature °C	Temperature °C
	A1	25	50	54	65

Table 2- Response time limits

Rate of rise of	Cat A1					
air temperature K min-1	Lowe	er limit	Upe	r limit		
	Min	S	Min	S		
1	29	0	40	20		
3	7	13	13	40		
5	4	9	8	20		
10	1	0	4	20		
20		30	2	20		
30		20	1	40		



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Essential characteristics	Clauses in EN 54-5:2017/ A1:2018	Regulatory classes	Performance
Operational reliability:			
Position of heat sensitive element	4.2.1		The heat sensitive element(s) or at least part of it, except elements with auxiliary functions (e.g.characteristic correctors), are a distance ≥15mm from the mounting surface of the point heat detector.
Individual alarm indication	4.2.2		Category A1 The heat detector is provided with an integral red visual indicator and can remain identified until the alarm is rese The visual indicator is visible from a distance of 6 m directly below the point heat detector, in an ambient ligh intensity up to 500 lx.
Connection of ancillary devices	4.2.3		Open or short circuit failures of connection to ancillary device do not prevent the correct operation of the detector
Monitoring of detachable point heat detectors	4.2.4		A fault condition is signaled when the detector is remove from the mounting base.
Manufacturer's adjustments	4.2.5		It is not possible to change the maufacture's settings expept by special means (e.g. a special code or tool, or b breaking or remove a seal).
Onsite adjustments of response behavior	4.2.6		N/A
Software controlled detectors	4.2.7	A1	The software documentation and the software design complies supplied by the manufacturer with the requirements of this standard.
Nominal activation conditions/Sensitivity:			
Directional dependence	4.3.1		The response time of the point dectetor do not unduly depend on the direction of airflow around the point heat detector.
Static response temperature	4.3.2		The response temperatures of the point heat detectors I between the minimum and maximum static response temperatures, according to the category of the point heat detector in Table 1 above.
Response times from typical application temperature	4.3.3		The response times of the point heat detector lie between the lower and upper response time limits for the appropriate point heat detector category in Table 2 above.
Response times from 25 °C	4.3.4		The response time at 3 K min ⁻¹ exceeds 7 min 13 s and th response time at 20 K min ⁻¹ exceeds 1 min 0 s.
Response times from high ambient temperature	4.3.5		No alarm or fault signal was given at high ambient temperatures appropriate to the anticipated service temepratures.



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1	1	
		3 K min ⁻¹ , Lower limit, 1 min 20 s and upper limit 13 m 40
		S.
Reproducibility	4.3.6	20 K min ⁻¹ , Lower limit, 12 s and upper limit 2 m 20 s. The response times of the point heat detectors lie
Reproducibility	4.3.0	between the lower ad upper response time limits specified in Table 2 above.
Response delay (response time):		
Additional test for suffix S point heat detectors	4.4.1	N/A
Additional test for suffix R point heat detectors	4.4.2	N/A
Tolerance to supply voltage:		
Variation in supply parameters	4.5	The point heat detector does not unduly depent on variation in the supply parameters and lie between the lower and upper response time limits specified in Table 2 above.
Durability of nominal activation conditions/Sensitivity:	-	
temperature resistance		
Cold (operational)	4.6.1.1	No alarm or fault signal was given during the transition to the conditioning temperature or during the period at the condition temperature Response time at 3 K min ⁻¹ was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6. <u>A1</u> : 20 K min ⁻¹ was not less than 30 s and did not exceed 30 s compared with the time obtained in 4.3.6
Dry heat (endurance)	4.6.1.2	No fault signal was given on reconnection attributable to the endurance conditioning
		Point heat detectorConditioningcategoryTemperature °C
		C 80 ±2
		D 95 ±2
		E 110 ±2
		F 125 ±2
		G 140 ±2
		Response time at 3 K min ⁻¹ was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.
		<u>A1</u> : 20 K min ⁻¹ was not less than 30 s and did not exceed 30 s compared with the time obtained in 4.3.6
Humidity resistance		
Damp heat, cyclic (operational)	4.6.2.1	No alarm or fault signal was given during the conditioning.
		•



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		Lower temperature: (25±3) °C Upper temperature: (40±2) °C
		Relative humidity:
		At lower temperature :≥ 95 %
		At upper temperature : (93 ±3) %
		Response time at 3 K min ⁻¹ was not less than 7 min 13 s
		and did not exceed 2 min 40 s compared with the time
		obtained in 4.3.6.
		A1: 20 K min ⁻¹ was not less than 30 s and did not exceed
		30 s compared with the time obtained in 4.3.6
Damp heat, steady-state	4.6.2.2	No fault signal was given on reconnection attributable to
(endurance)	4.0.2.2	the endurance conditioning.
(endurance)		the endurance conditioning.
		Conditioning
		Temperature : 40 ±2 °C
		Relative Humidity: 93 ±3 %
		Duration : 21 days
		Response time at 3 K min ⁻¹ was not less than 7 min 13 s
		and did not exceed 2 min 40 s compared with the time
		obtained in 4.3.6.
		A1: 20 K min ⁻¹ was not less than 30 s and did not exceed
		30 s compared with the time obtained in 4.3.6
Corrosion resistance		
	4.6.2	
Sulphur dioxide (SO ₂)	4.6.3	No fault signal was given on reconnection attributable to
corrosion (endurance)		the endurance conditioning.
		Conditioning
		Temperature : 25 ±2 °C
		Relative Humidity: 93 ±3 %
		SO2 concentration: 25 ±5 ppm (by volume)
		Duration : 21 days
		Duration. 21 uays
		Response time at 3 K min ⁻¹ was not less than 7 min 13 s
		and did not exceed 2 min 40 s compared with the time
		obtained in 4.3.6.
		A1: 20 K min ⁻¹ was not less than 30 s and did not exceed
		$\overline{30}$ s compared with the time obtained in 4.3.6
Vibration resistance		
	4.6.4.4	No slavna an faith star string string string at
Shock (operational)	4.6.4.1	No alarm or fault signal was given during the
		conditioning period or an additional 2 min.
		For specimen with a mass ≤ 4,75 kg :
		Shock pulse type: Half sine
		Pulse duration : 6 ms
		Peak acceleration: 10X (100-20M) ms-2 (M is specimen
		mass in Kg)
		Number of directions: 6



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		Pulses per direction: 3
		Response time at 3 K min ⁻¹ was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.
		<u>A1</u> : 20 K min ⁻¹ was not less than 30 s and did not exceed 30 s compared with the time obtained in 4.3.6
Impact (operational)	4.6.4.2	No alarm or fault signal was given during the conditioning period or an additional 2 min.
		Conditioning: Impact energy: 1,9 ±0,1 J Hammer velocity: 1,5 ±0,13 ms ⁻¹ Number of impacts: 1
		Response time at 3 K min ⁻¹ was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.
		<u>A1</u> : 20 K min ⁻¹ was not less than 30 s and did not exceed 30 s compared with the time obtained in 4.3.6
Vibration, sinusoidal (operational)	4.6.4.3	No fault signal was given during the conditioning Conditioning: Frequency range: 10 to 150 Hz Acceleration amplitude: 5 ms ⁻² (≈0,5 g _n) Number of axes : 3 Sweep rate: 1 octave min ⁻¹ Number of sweep cycles: 1 per axis
		Response time at 3 K min ⁻¹ was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6. <u>A1</u> : 20 K min ⁻¹ was not less than 30 s and did not exceed 30 s compared with the time obtained in 4.3.6
Vibration, sinusoidal (endurance)	4.6.4.4	No fault signal was given on reconnection attributable to the endurance conditioning.
		Conditioning: Frequency range: 10 to 150 Hz
		Acceleration amplitude: 10 ms ⁻² (≈1,0 g _n) Number of axes : 3
		Sweep rate: 1 octave min ⁻¹ Number of sweep cycles: 20 per axis
		Response time at 3 K min ⁻¹ was not less than 7 min 13 s
		and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.
		<u>A1</u> : 20 K min ⁻¹ was not less than 30 s and did not exceed 30 s compared with the time obtained in 4.3.6
Electrical stability EMC	4.6.5	Compliance in EN 50130-4:2011 and No fault signal was
immunity (operational)		given during the conditioning.



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Response time at 3 K min⁻¹ was not less than 7 min 13 s and did not exceed 2 min 40 s compared with the time obtained in 4.3.6.

<u>A1</u>: 20 K min⁻¹ was not less than 30 s and did not exceed 30 s compared with the time obtained in 4.3.6

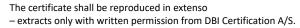
Essential characteristics	Clauses in EN 54-7:2018	Regulatory classes	Performance
Operational reliability:			
Individual alarm indication	4.2.1		The visual indicator(s) are visible from a distance of 6 m in an ambient light intensity up to 500 lx.
Connection of ancillary devices	4.2.2		Open or short circuit failures of connection to ancillary device d not prevent the correct operation of the detector
Vionitoring of detachable detectors	4.2.3		A fault condition is signaled whe the detector is removed from th mounting base.
Manufacturer´s adjustments	4.2.4		It is not possible to adjust the detector settings without the us of a special tool to access into the detector or use of a code to enabling entry into the panel programming software.
On site adjustment of response behavior	4.2.5	None	The mode(s) of operation are adjustable from the Control and Indicating Equipment by use of loop communication protocol. Access to enable mode changes is by software control of the protocol communication.
Protection against the ingress of foreign bodies	4.2.6		The chamber is designed so tha a sphere of diameter (1,3±0,05) mm cannot pass into the sensor chamber.
Response to slowly developing fires	4.2.7		The provision of "drift compensation" (e.g. to compensate for sensor drift due to the build-up of dirt in the detector), does not lead to a significant reduction in the detectors sensitivity to slowly developing fires.
Software controlled detectors	4.2.8		The software documentation and the software design complies with the requirements of EN 54- 7:2018.
Nominal activation conditions/sensitivity:			
Repeatability	4.3.1	Threshold	Ratio of response values m_{max} : $m_{min} \le 1.6$



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	T		Lower response value, m _{max} :m _{min}
			<u>></u> 0.05 dB m ⁻¹
Directional dependence	4.3.2		Ratio of response values
			m _{max} :m _{min} <u><</u> 1.6
			Lower response value, m_{max} : m_{min}
	L		<u>></u> 0.05 dB m ⁻¹
Reproducibility	4.3.3		Ratio of response values $m_{max}:\overline{m}$
			<u><</u> 1.33
			Ratio of the response values
			<u>m</u> : m _{min} <u>≤</u> 1.5
			Lower response value, m _{min} <u>></u>
			0.05 dB m ⁻¹
Response delay (response time):			
Air movement	4.4.1		Ratio is > 0.0625 and < 1.60
			and the point smoke detector did
			not emit a fault nor alarm signal
			during the test with aerosol-free
	_		air
Dazzling	4.4.2		The specimen did not emit
			neither an alarm nor a fault
			signal and Ratio of response
			thresholds $m_{max}:m_{min} \leq 1.6$
	+	-	
Tolerance to supply voltage: Variation in supply parameters	4.5	-	Ratio of response values
	4.5		$m_{max}:m_{min} < 1.6$
			Lower response value, m _{min} >
			0.05 dB m ⁻¹
Performance parameters under fire conditions:	+		
Fire sensitivity	4.6		Evaluated as meeting the
,			requirements of TF2 toTF5
Durability of nominal activation			
conditions/Sensitivity:			
temperature resistance			
Cold (operational)	4.7.1.1		The specimen did not emit
			neither an alarm nor a fault
			signal and Ratio of response
	<u> </u>		values m _{max} :m _{min} ≤ 1.6
Dry heat (operational)	4.7.1.2		The specimen did not emit
			neither an alarm nor a fault
			signal and Ratio of response
	<u> </u>	- -	values m _{max} :m _{min} <u><</u> 1.6
Humidity resistance Damp heat, steady-state (operational)	4.7.2.1		The specimen did not emit
Damp near, steauy-state (Operational)	4.7.2.1		neither an alarm nor a fault
			signal and ratio of response
			values $m_{max}:m_{min} \le 1.6$
Damp heat, steady-state (endurance)	4.7.2.2		No fault signal, attributable to
Damp lical, sicaly-slate (eliuli dille)	4.7.2.2		-
			the endurance conditioning was given on reconnection of the
			-
			specimen and Ratio of response values m_{max} : $m_{min} \leq 1.6$
Corrosion resistance	+	- -	Values IIImax.IIImin > 1.0
Sulphur dioxide (SO ₂) corrosion (endurance)	4.7.3	- -	No fault signal, attributable to
			the endurance conditioning was
			given on reconnection of the
	<u> </u>		given on reconnection of the







		_	specimen and Ratio of response values m_{max} : $m_{min} \le 1.6$
Vibration resistance Shock (operational)	4.7.4.1		No fault signal given from the specimen during the conditioning period or the additional 2 min. and Ratio of response values $m_{max}:m_{min} \leq 1.6$
Impact (operational)	4.7.4.2		No fault signal given from the specimen during the conditioning period or the additional 2 min. and Ratio of response values $m_{max}:m_{min} \leq 1.6$
Vibration, sinusoidal (operational)	4.7.4.3		No fault signal given from the specimen during the conditioning and Ratio of response values m_{max} : $m_{min} \le 1.6$
Vibration, sinusoidal (endurance)	4.7.4.4		No fault signal, attributable to the endurance conditioning was given on reconnection of the specimen and Ratio of response values m_{max} : $m_{min} \leq 1.6$
Electrical stability EMC immunity (operational) a) Electrostatic discharge (operational) b) Radiated electromagnetic fields (operational) c) Conducted disturbances(operational) d) Fast transient bursts (operational) e) Slow high energy voltage surge (operational)	4.7.5		No alarm or fault signal given during the conditioning and Ratio of response values m _{max} :m _{min} ≤ 1.6

Essential characteristics	Clauses in EN 54-17:2005	Performance
erformance under fire conditions	5.2 ¹⁾	Pass
perational reliability	4	Pass
urability of operational reliability; emperature resistance	5.4, 5.5	Pass
urability of operational reliability; ibration resistance	5.9 to 5.12	Pass
urability of operational reliability; umidity resistance	5.6, 5.7	Pass
urability of operational reliability; orrosion resistance	5.8	Pass
urability of operational reliability; lectrical stability	5.3, 5.13	Pass

Since the heat sensor can be used as a multisensor where the heat sensor enhances the response characteristics of the smoke detector (type), the product is tested and approved according to **CEA4021:2003**.

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Annex 2

TEST DOCUMENTATION

Accredited Laboratory	Report no.	Date
DNV	99-1491 Revision: 02	1999-12-03, Rev. 02: 2000-01-04
DNV	2000-1178 Revision: 02	2000-02-15, Rev. 02: 2000-03-13
ANPI	BFS/DE/1057	2007-06-29
ANPI	BFS/REDI/154	2005-06-03 Addendum nr. 1: 2008-06-20 Addendum nr. 2: 2009-04-22
ANPI	BFS/REDI/234	2009-01-28
ANPI	BFS/REDI/155	2005-06-16 Addendum nr. 1: 2008-06-20 Addendum nr. 2: 2008-06-27
NEMKO	E18217.00	2018-11-15

TECHNICAL BASIS

File Number		Title	
BoM BHH-220	Bill of Materials Report		
ВоМ ВНН-320	Bill of Materials Report		
BoM BHH-520	Bill of Materials Report		
ВоМ ВНН-520 N	Bill of Materials Report		
вом внн-520 ех	Bill of Materials Report		



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